

- Low profile (10 mm)
- Hollow, floating shaft
- No bearings or other contact elements
- High resolution and unparalleled precision
- High tolerance to temperature extremes, shock, EMI, RFI and magnetic fields
- Very low weight
- Holistic signal generation
- Digital interfaces for absolute position

### General

Angular resolution	18-20 bit
Maximum tested static error	±0.010°
Extended accuracy static error	±0.008°
Maximum operational speed	4,000 rpm
Measurement range	Single turn, unlimited
Rotation direction	Adjustable CW/CCW

<sup>\*</sup> Default same direction from bottom side of the encoder

#### Mechanical

Allowable mounting eccentricity	±0.1 mm
Allowable axial mounting tolerance	±0.1 mm
Rotor inertia	684 gr · mm²
Total weight	30 gr
Outer Ø /Inner Ø/ Height	58 / 20 / 10 mm
Material (stator, rotor)	Ultem™ polymer / TRVX-50

The holistic structure of the Electric Encoder™ makes it unique: Its output reading is the averaged outcome of the entire area of the rotor. This feature allows the EE a tolerant mechanical mounting and to deliver outstanding precision.

Due to the absence of components such as ball bearings, flexible couplers, glass discs, light sources and detectors along with very low power consumption enables the EE to deliver virtually failure-free performance in nearly all types of conditions.

The internally shielded, DC - operated EE includes an electric field generator, a field receiver, sinusoidal-shaped dielectric rotor, and processing electronics.

The EE output is a digital serial synchronous with absolute position single turn.

This combination of high precision, low profile and, low weight has made Netzer Precision encoders highly reliable and particularly well suited to a wide variety of industrial automation and harsh environment applications.

### Electrical

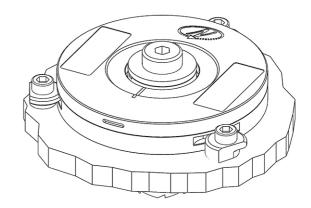
Supply voltage	5V ± 5%
Current consumption	90 mA
Interconnection	Shielded cable

#### Environmental

EMC	IEC 6100-6-2, IEC 6100-6-4
Operating temperature	-40°C to +85°C
Storage temperature	-50°C to +100°C
Relative humidity	98% Non condensing
Shock endurance	100 g for 11 ms
Vibration endurance	20 g 10 – 2000 Hz
Protection	IP 40



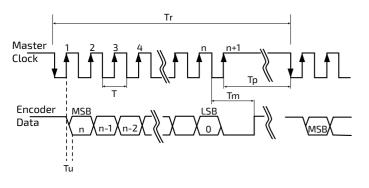




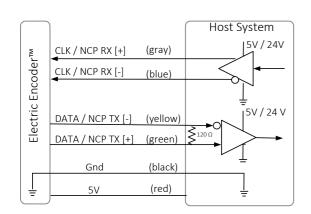


# Digital SSi Interface

Synchronous Serial Interface (SSi) is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations
n	Total number of data bits	12 - 22
Т	Clock period	
f= 1/T	Clock frequency	0.1 - 5.0 MHz
Tu	Bit update time	90 nsec
Тр	Pause time	26 - ∞ µsec
Tm	Monoflop time	>25 µsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 μsec
fr=1/Tr	Data request frequency	



## SSi / BiSS output signal parameters

Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock frequency	0.1 ÷ 5.0 MHz
Position update rate	35 kHz (Optional - up to 375 kHz)

### SSi / BiSS interface wires color code

Clock +	Grey	Clock	
Clock -	Blue	Clock	
Data -	Yellow	Data	
Data +	Green	Dala	
GND	Black	Ground	
+5V	Red	Power supply	

### Software tools: (SSi / BiSS - C)



using the factory supplied <u>Electric Encoder Explorer software</u>, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.

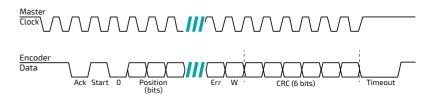






## Digital BiSS-C Interface

BiSS – C Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS-C interface as the SSi is based on RS-422 standards.

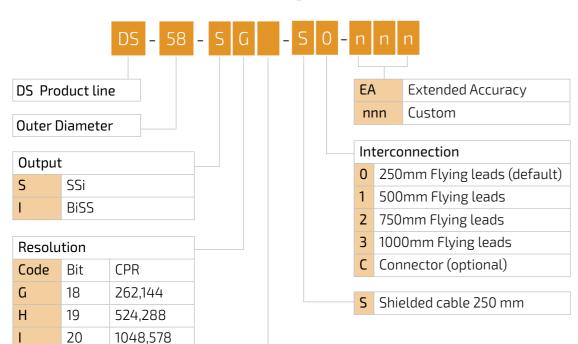


Bit #		Description	Default	Length
28	Ack	Period during which the encoder calculates the absolute position, one clock cycle	0	1/clock
27	Start	Encoder signal for "start" data transmit	1	1 bit
26	"0"	"start" bit follower	0	1 bit
825	AP	Absolute Position encoder data		
7	Error	Error (BIT optional)	1	1 bit
6	Warn.	Warning (non active)	1	1 bit
05	CRC	The CRC polynomial for position, error and warning data is: $x^6 + x^1 + x^0$ . It is transmitted MSB first and inverted.  The start bit and "0" bit are omitted from the CRC calculation.		6 bits
	Timeout	Elapse between the sequential "start"request cycle's.		25 μs

BIT (Build In Test): optional

None BIT

# **Ordering Code**



## **Cable Information**

Cable: 30 AWG twisted pair (3)

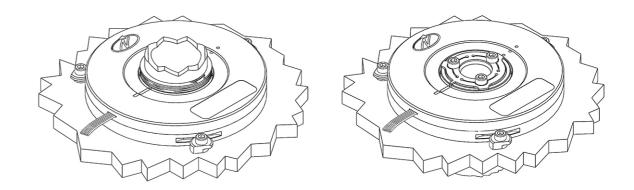
(30 AWG 25/0.05 tinned copper, Insulation: ETFE  $\emptyset$  0.12-0.15 to  $\emptyset$  0.6  $\pm$  0.05 0D)

Temperature rating: -60° to +150° C

Braided shield: Thinned copper braided 95% min. coverage

Jacket: 0.4-0.5 silicon rubber Ø3.45 ±0.2 OD

Pair#	Color	30 AWG twisted pairs (3) 30 AWG	i single
A1-A2	Red / Black	0.015 + insulate	ed wire
A3-A4	Gray / Blue	Braided shield	
A5-A6	Green / Yellow	Jacket 0.4-0.5 mm	
		Ø0.6±0	.05 mm
		○ Ø 3.45 ±0.2 mm	



### Related documents

DS-58 User Manual: Mechanical, Electrical and calibration setup.

## **Optional Accessories**

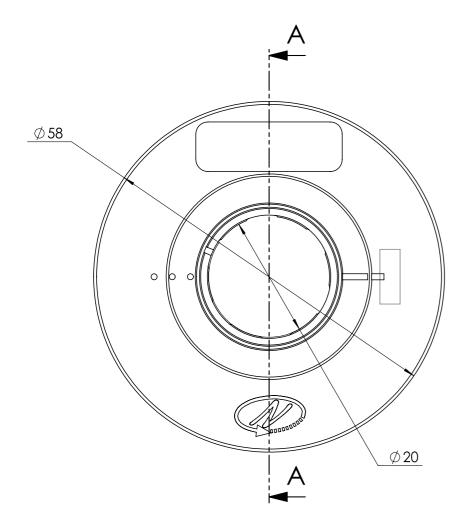
### Demonstration Kit

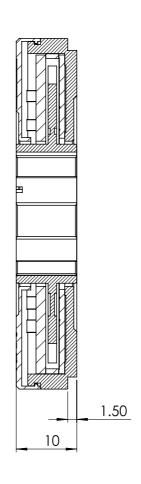
DKIT-DS-58-SG-S0 - SSi interface

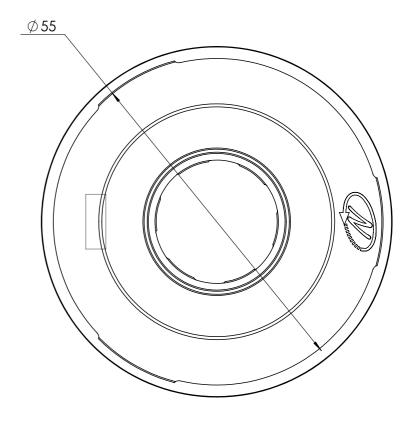
DKIT-DS-58-IG-SO - BiSS interface

The Demo-kit Includes, mounted encoder on rotary jig, and RS-422 to USB converter.







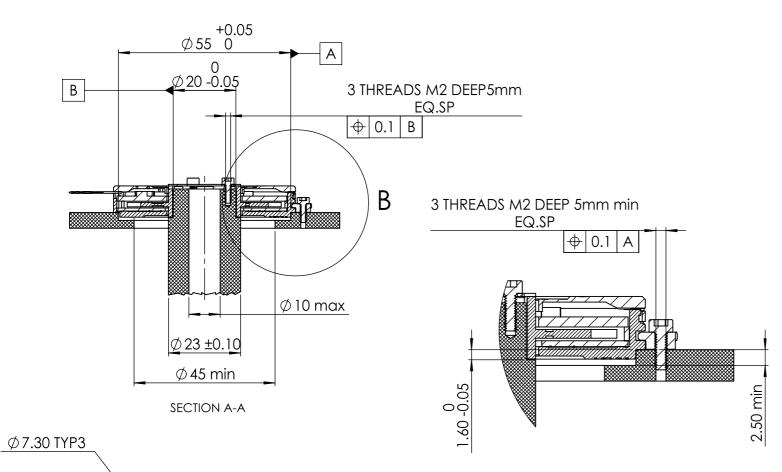


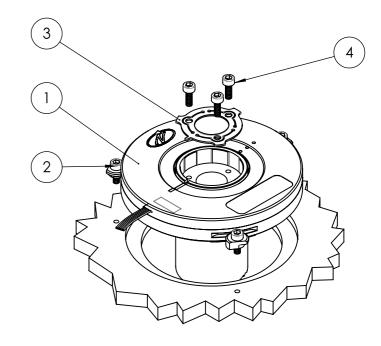
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	Dimensions are in: mm	Surface finish: N6	
Linear tolerances			
	0.5-4.9: ±0.05 mm	5-30: ±0.1 mm	
	31-120: ±0.15 mm	121-400: ±0.2 mm	

# Shaft - End installation (step)





	A

Unless Otherwise Specified		
Dimensions are in: mm	Surface finish: N6	
Linear tolerances		
0.5-4.9: ±0.05 mm	5-30: ±0.1 mm	
31-120: ±0.15 mm	121-400: ±0.2 mm	

No	Part			Description	QTY.
1	DS-58	Included		DS-58 encoder	1
2	EAPK005	Included	Kit	3 x M2 encoder clamps	1
3	MA-DS58-20-004 Optional	Shaft end	Shaft end spring	1	
4		Optional	installation kit	Screw DIN 912 M2x4	3

Critical dimensions marked with "\*"

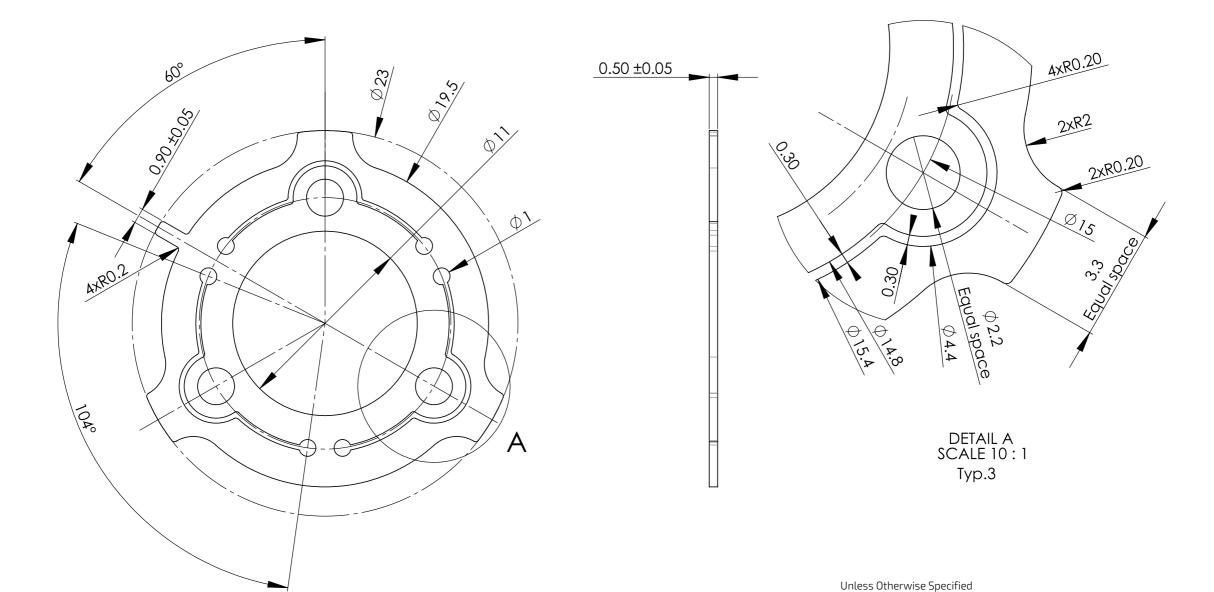
### WARNING



Do not use Loctite or other glues containing Cyanoacrylate. Do not use Loctite of other glues containing cyanoaci, a
We recommend to use 3M glue - Scotch-Weld™ Epoxy Adhesive EC-2216 B/A.

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Dimensions are in: mm Surface finish: N6

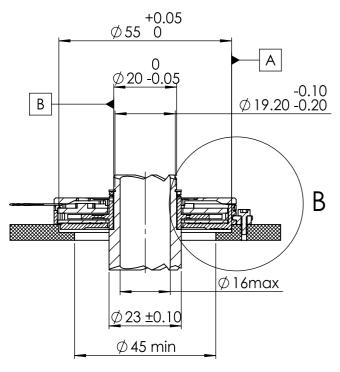
5-30: ±0.1 mm

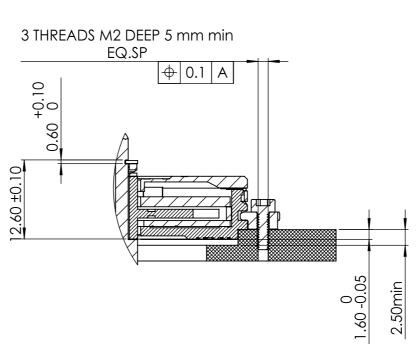
121-400: ±0.2 mm

Linear tolerances 0.5-4.9: ±0.05 mm

31-120: ±0.15 mm

# Shaft - MID installation (step)





Unless Otherwise Specified

Linear tolerances

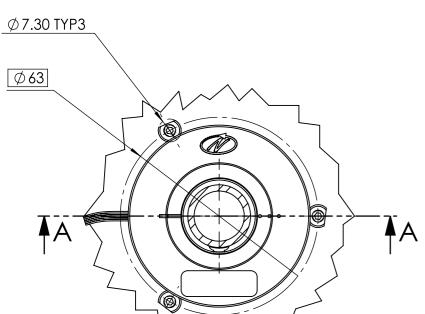
0.5-4.9: ±0.05 mm

31-120: ±0.15 mm

Dimensions are in: mm Surface finish: N6

5-30: ±0.1 mm

121-400: ±0.2 mm



SECTION A-A

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No	Part			Description	QTY.
1	DS-58	Included		DS-58 encoder	1
2	EAPK005	Included	Kit	3 x M2 encoder clamps	1
3			Shaft end	C-ring	1
4	MA-DS58-20-002	Optional	installation kit	Mid of shaft spring	1

Critical dimensions marked with "\*"

### WARNING



Do not use Loctite or other glues containing Cyanoacrylate.
We recommend to use 3M glue - Scotch-Weld™ Epoxy
Adhesive EC-2216 B/A.