





The DS-90 is a member of the DS series of Electric Encoders<sup>™</sup>, based on Netzer Precision proprietary technology. The Electric Encoder<sup>™</sup> offers many advantages - some unparalleled

- Low profile (10 mm)
- Hollow, floating shaft
- No bearings or other contacting elements
- High resolution and precision
- High tolerance to temperature extremes, shock, moisture, EMI, RFI and Magnetic fields
- Very low weight
- Holistic signal generation
- Analog or Digital interfaces

#### General

Angular resolution	19-21 bit
Maximum tested static error	±0.010°
Extended accuracy static error	±0.006°
Maximum operational speed	2000 rpm
Measurement range	Unlimited rotation
Rotation direction	Adjustable CW/CCW*
Power On - Max. operational speed	3.3 RPM <=20°/sec
Build In test BIT	Optional

 $^{\ast}$  Default same direction from bottom side of the encoder

# Mechanical

Allowable mounting eccentricity	±0.1 mm
Allowable axial mounting tolerance	±0.1 mm
Rotor inertia	4,242 gr · mm²
Total weight	55 gr
Outer Ø /Inner Ø/ Height	90 / 50 / 10 mm
Material (stator, rotor)	Ultem™ polymer / TRVX-50

The Electric Encoder<sup>™</sup> is unique in being holistic, i.e., its output reading is the averaged outcome of the whole area of the rotor, This feature makes the Electric Encoder<sup>™</sup> forgiving to mounting tolerances, mechanical wander etc.

The absence of components such as ball bearings, flexible couplers, glass disc, light sources and detectors, along with very low power consumption makes the Electric Encoder<sup>™</sup> virtually failure free.

The DC operated Electric Encoder<sup>™</sup> includes an electric field generator, a field receiver, a sinusoidal shaped dielectric rotor, and processing electronics.

The output signals of Electric Encoder<sup>TM</sup> are analog Sine / Cosine representing the rotation angle. The digital outputs are obtained by further processing - which may be either internal or external to the encoder.

The combination of precision, low profile, low weight and high reliability have made Netzer Precision encoders particularly suitable to a wide variety of critical applications including, but not limited to medical equipment and aerospace.

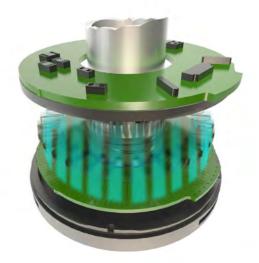
# Electrical

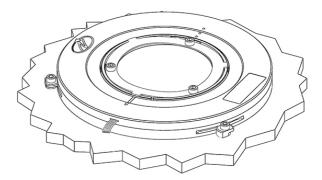
Supply voltage	5V ± 5%
Interconnection	Shielded cable
Cable length	1,500 mm MAX
Current consumption	90 mA

# Environmental

EMC	IEC 6100-6-2, IEC 6100-6-4
Operating temperature range	-40°C to +85°C
Storage temperature	-50°C to +100°C
Relative humidity	98% Non condensing
Shock endurance	100 g for 11 ms
Vibration endurance	20 g 10 – 2000 Hz
Protection	IP 40











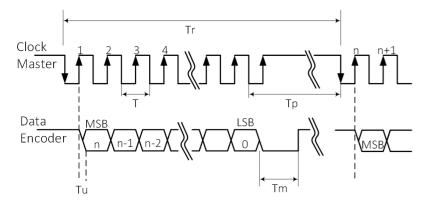
Netzer

320.202

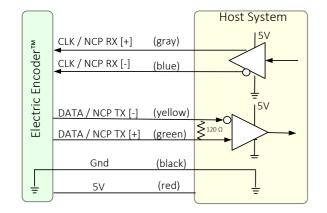


# Digital SSi Interface

Synchronous Serial Interface (**SSI**) is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations
n	Total number of data bits	12 - 21
Т	Clock period	
f= 1/T	Clock frequency	0.1 - 5.0 MHz
Tu	Bit update time	90 nsec
Тр	Pause time	26 - ∞ µsec
Tm	Monoflop time	>25 µsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 µsec
fr=1/Tr	Data request frequency	



# SSi / BiSS Output signal parameters

Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock frequency	0.1 ÷ 5.0 MHz
Position update rate (Max)	35 kHz (Optional - up to 375 kHz)

# SSi / BiSS interface wires color code

Clock +	Grey	Clock	
Clock -	Blue	CIUCK	
Data -	Yellow	Data	
Data +	Green	Dala	
GND	Black	Ground	
+5V	Red	Power supply	

# Software tools: (SSi / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied <u>Electric Encoder Explorer software</u>, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.



# Digital BiSS-C Interface

**BiSS** – **C** Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode). The BiSS-C interface as the SSi is based on RS-422 standards.

# Master Clock



bit #		Description	Default	Length
29	Ack	Period during which the encoder calculates the absolute position , one clock cycle	0	1/clock
28	Start	Encoder signal for "start" data transmit	1	1 bit
27	"0"	"start" bit follower	0	1 bit
826	AP	Absolute Position encoder data		
7	Error	Error (amplitude levels)	1	1 bit
6	Warn.	Warning (non active)	1	1 bit
05	CRC	The CRC polynomial for position, error and warning data is: $x6 + x1 + x0$ . It is transmitted MSB first and inverted.		6 bits
		The start bit and "0" bit are omitted from the		
		CRC calculation.		
	Time- out	Elapse between the sequential "start"request cycle's.		25 µs





# Ordering Code

EA

1

С

nnn

Extended Accuracy

0 250mm Flying leads (default)

500mm Flying leads

2 750mm Flying leads

3 1000mm Flying leads

**S** Shielded cable

Connector (optional)

**R** Strain relief & shielded cable

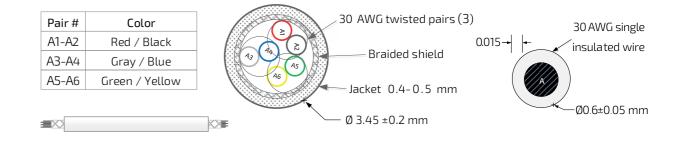
Custom

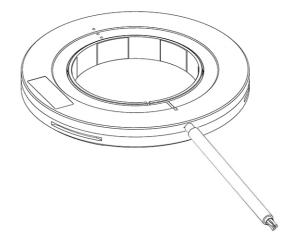
Interconnection

# **Cable Information**



(30 AWG 25/0.05 tinned copper, Insulation: ETFE Ø 0.12-0.15 to Ø 0.6  $\pm$  0.05 OD) Temperature rating: -60° to +150° C Braided shield: Thinned copper braided 95% min. coverage Jacket: 0.4-0.5 silicon rubber Ø3.45  $\pm$ 0.2 OD





Related documents DS-90 User Manual: Mechanical, Electrical and calibration setup.

# **Optional Accessories**

#### **Demonstration Kit**

DKIT-DS-90-SH-SO: (SSi Interface) DKIT-DS-90-IH-SO: (BiSS interface) Includes, mounted encoder on rotary jig, and RS-422 to USB converter.

# Output S S SSi BiSS SSi Resolution SSi Code Bit CPR H 19 524,288 I 20 1,048,578

\* SSi only

DS Product line

**Outer Diameter** 

#### BIT (Build In Test): optional

2,097,156

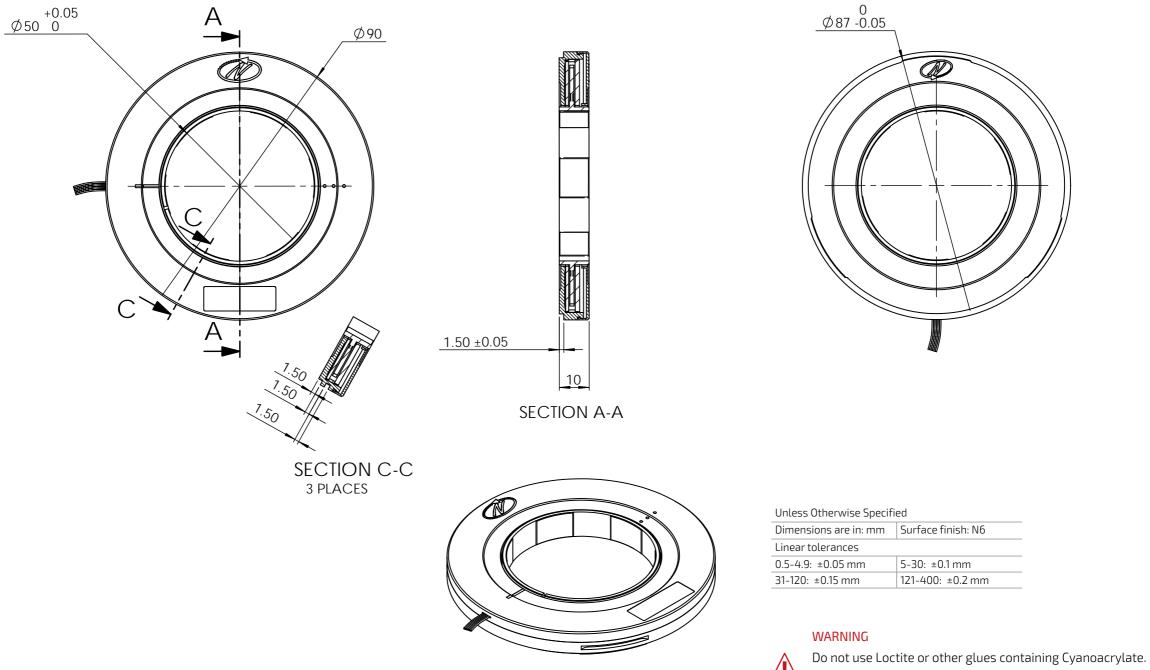
21\*

[]	none
В	BIT





ICD DS-90-SH-S0 / DS-90-IH-S0

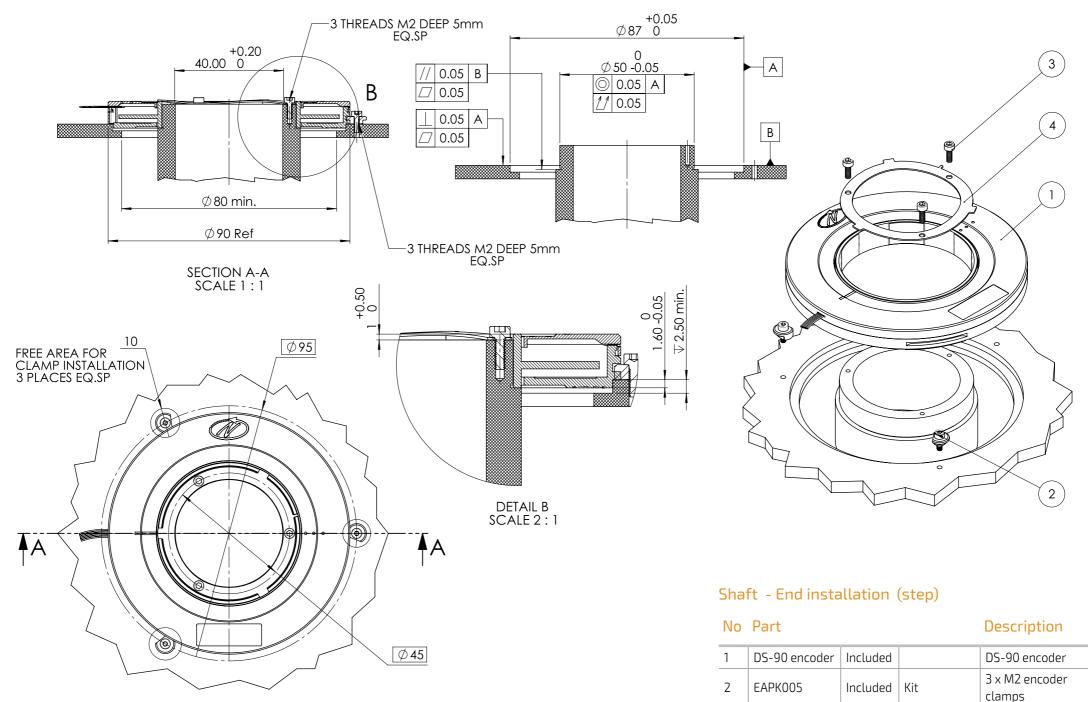


Do not use Loctite or other glues containing Lyanoacrylate. We recommend to use 3M glue - Scotch-Weld™ Epoxy Adhesive EC-2216 B/A.

DATA SHEET







# Unless Otherwise Specified

Dimensions are in: mm	Surface finish: N6	
Linear tolerances		
0.5-4.9: ±0.05 mm	5-30: ±0.1 mm	
31-120: ±0.15 mm	121-400: ±0.2 mm	

# WARNING

Do not use Loctite or other glues containing Cyanoacrylate. We recommend to use 3M glue - Scotch-Weld™ Epoxy Adhesive EC-2216 B/A.

Critical dimensions marked with "\*"

MA-DS90-004

3

4

Bolt DIN 912 M2×4

DS-90 wave spring

SIMP

Shaft End

kit

installation

Optional

QTY.

per kit

1

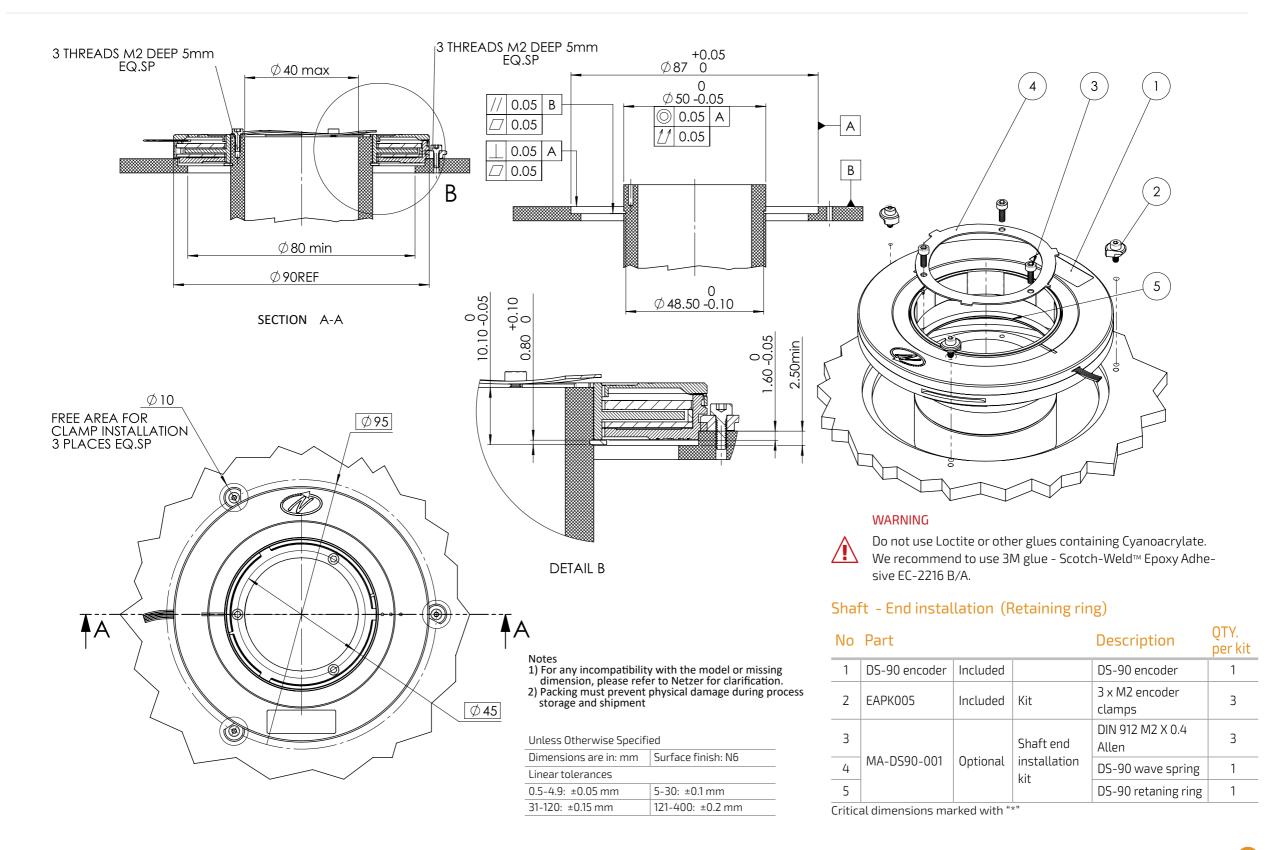
3

3

1



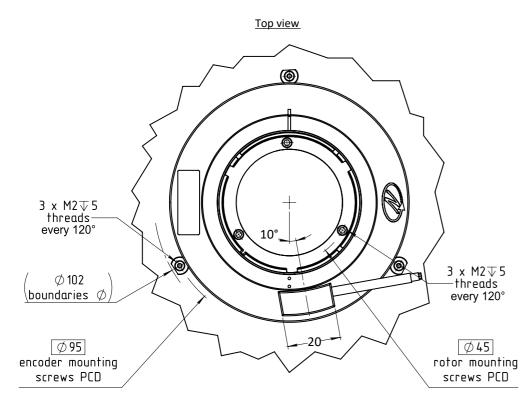




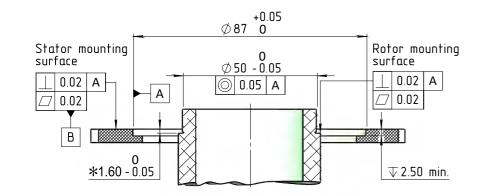




DS-90 Strain relief model



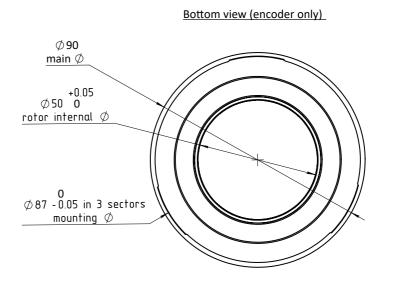
Mounting requirements



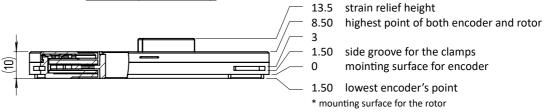
Recommended height between stator and rotor mounting surfaces is
 1.6 mm, despite the nominal dimension in the encoder is
 1.5 mm.

The difference is because of possible inaccuracies in a mounting assembly, as the positive error could be filled by shims, while the negative error is impossible to solve rather than by machining.

Unless Otherwise Specified		
Dimensions are in: mm Surface finish: N6		
Linear tolerances		
0.5-4.9: ±0.05 mm	5-30: ±0.1 mm	
31-120: ±0.15 mm	121-400: ±0.2 mm	



Side view (without cable)



#### WARNING

Do not use Loctite or other glues containing Cyanoacrylate. We recommend to use 3M glue - Scotch-Weld™ Epoxy Adhe-

sive EC-2216 B/A.

# Shaft - End installation (Retaining ring)

No	Part			Description	QTY. per kit
1	DS-90 encoder	Included		DS-90 encoder	1
2	EAPK005	Included	Kit	3 x M2 encoder	3
				clamps	
3				DIN 912 M2 X 0.4	3
		MA-DS90-001 Optional	Shaft end Optional installation kit	Allen	
4	MA-DS90-001			DS-90 wave spring	1
5			INIL .	DS-90 retaning ring	1
Critical dimensions marked with "*"					

Critical dimensions marked with "\*